

**2022 YJC Preliminary Examination H2 Physics Paper 1 Answer Key**

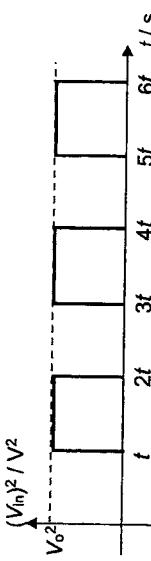
Question	Answer	Question	Answer	Question	Answer
1	C	11	C	21	A
2	A	12	D	22	A
3	C	13	B	23	A
4	D	14	C	24	C
5	D	15	A	25	D
6	D	16	B	26	B
7	C	17	C	27	A
8	B	18	D	28	C
9	A	19	B	29	A
10	A	20	C	30	C

S/N	Ans	Explanation
1	C	Units of $\mu = \frac{Ns}{kg} = A\text{ s}^2\text{ kg}^{-1}$
2	A	$X = P - R = P + (-R)$ Hence vector R needs to change to the opposite direction before adding to P
3	C	Distance travelled during $0.20\text{ m s}^{-2}$ acceleration = $\frac{20^2}{2(0.20)} = 1000\text{ m}$ Distance travelled for the $0.40\text{ m s}^{-2}$ deceleration = $\frac{20^2}{2(0.40)} = 500\text{ m}$ Total time travel = $\frac{20}{(0.20)} + \frac{1500}{20} + \frac{20}{(0.40)} = 225\text{ s}$
4	D	Given that the reading is smaller than the person's mass, this means that the normal force is less than its weight. Thus, the resultant force at this instant is downwards. Hence, the person could be moving downwards with increasing speed or moving upwards with decreasing speed

5	D	Taking all the masses as a system, $F = 6a$ $a = F/6$ Applying $F = ma$ for the 1kg mass $F$ -Force by $2kg = a$ $F$ -Force by $2kg = F/6$ $F$ -Force by $2kg = 5F/6$
6	D	For elastic collision, momentum and total KE must be conserved. Only option D fulfilled both the conditions. For Option D: Initial total momentum = $(0.50)(4.0) + (0.50)(1.0) = 2.5\text{ N s}^{-1}$ Final total momentum = $(0.50)(1.0) + (0.50)(4.0) = 2.5\text{ N s}^{-1}$ Initial total KE = $\frac{1}{2}(0.50)(4.0)^2 + \frac{1}{2}(0.50)(1.0)^2 = 4.25\text{ J}$ Final total KE = $\frac{1}{2}(0.50)(1.0)^2 + \frac{1}{2}(0.50)(4.0)^2 = 4.25\text{ J}$
7	C	Extra knowledge: since the object has the same mass, and it is head on elastic collision, the object will swap their velocities before and after collision Weight = $(Tension)\cos(30^\circ)$ $F = (Tension)\sin(30^\circ)$ Hence, $F/Weight = \tan(30^\circ)$ $F = 170\text{ N}$
8	B	By conservation of energy, Loss in GPE = Gain in KE + W.D by resistive force $(600)(80 - h)(9.81) = [\frac{1}{2}(600)(12.0)^2 - q] + (200)(1500)$ $h = 22\text{ m}$
9	A	Force by engine + (Weight) $\sin(6.0^\circ)$ – resistive force = 0 Force by engine = $462\text{ N}$ Power output by engine = $(462)(30) = 14\text{ kW}$
10	A	Frictional force is the only horizontal force and hence it will be the only force that contributes to the centripetal force. Since centripetal force is towards the right at this instant, frictional force is rightwards.

11	C	$F_n = ma$ $mg = ma$	Since $\mathbf{g} = -\frac{d\phi}{dr} = -\frac{\Delta\phi}{\Delta r}$ for a uniform gravitational field $\frac{m\Delta\phi}{\Delta r} = \frac{E}{x} = ma$ $a = \frac{E}{mx}$
12	D	For simple harmonic motion, $a = -\omega^2 x$ . Hence the gradient of an a-x graph is $-\omega^2$ $ \text{Gradient}  = \left(\frac{2\pi}{T}\right)^2 = \frac{4\pi^2}{T^2}$	When the period of oscillation is doubled, the gradient of the graph is one quarter of the original graph.
13	B	$v = f\lambda \Rightarrow 340 = (500)\lambda \Rightarrow \lambda = 0.68 \text{ m}$	
14	C	$I_1$ is the same regardless of the orientation. (Students to understand that $I_1$ is half the intensity of the incident unpolarized light) $I_2$ will change according to Malus' Law ( $I_2 = I_1 \cos^2 \theta$ ) where $\theta$ is the angle between the transmission axes of the polarisers.	
15	A	There are effectively 6 loops spanned over a distance of 1.5 m Thus, length of one loop = $\frac{1}{2}\lambda = \frac{1.5}{6} = 0.50 \text{ m}$	
16	B	$d \sin \theta = n\lambda$ $\left(\frac{10^{-3}}{1200}\right) \sin 35.0^\circ = (1)\lambda$ $\lambda = 4.78 \times 10^{-7} \text{ m} = 478 \text{ nm}$	
17	C	Assuming that the rate of heat loss is constant, a longer time interval Q compared to time interval S means that more thermal energy is given out during the process of condensation than freezing. For the same mass, more thermal energy implies that the specific latent heat of vapourisation is greater than its specific latent heat of fusion.	

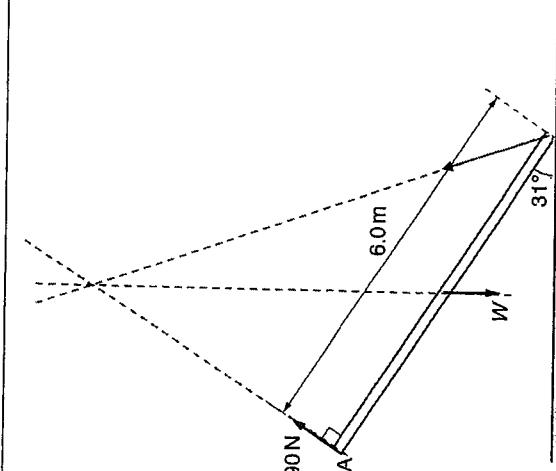
18	D	With the reduction in the volume of gas, the distance between the walls of the gas container is reduced, leading to an increase in the frequency of the collisions of the gas molecules with the walls. Hence the rate of change of momentum and hence force that the gas molecules experience increased. According to Newton's third law, the force and pressure acting on the walls increases. With constant temperature, the kinetic energy and speed of the gas molecules remains unchanged.	
19	B	$W_{on} = -\rho(V_f - V_i) = -1.3 \times 10^5 \times (3.6 - 1.3) \times 10^{-4}$ $= -29.9 \text{ J (expansion)}$ $\Delta U = Q_{in} + W_{on} = (+24) + (-29.9)$ $= -5.9 \approx -6 \text{ J}$	
20	C	With the electric field pointing downwards, the electric force acting on the +Q and -Q is downwards and upwards respectively. That would lead to a resultant force of zero and a resultant torque in the anti-clockwise direction.	
21	A	Work done = $\Delta EPE = q\Delta V$ Since P and Q are at the same distance away from the positive point charge, the potential at P and Q are the same, i.e. $\Delta V = 0$ $W = 0$	
22	A	$I = nAvq$ Thus the average drift velocity is directly proportional to the current and inversely proportional to the square of the diameter. When the current is doubled and the diameter is doubled, the average drift velocity is halved.	
23	A	$P_{device} = I^2 R$ $4.0 = I^2 \times 20$ $I_{device} = 0.447 \text{ A}$ $P_{device} = IV$ $4.0 = 0.447 V$ $V_{device} = 8.94 \text{ V}$ $V_{monitor} = IR$ $16 - 8.94 = 0.447 R_{monitor}$ $R_{monitor} = 15.7 \approx 16 \Omega$	
24	C	Given that the ammeter reading is zero, the p.d. across the $100 \Omega$ is the same as the p.d. across the $200 \Omega$ , i.e. $V_{100\Omega} = V_{200\Omega}$ Using potential divider, $\frac{100}{100+50} \times 12 = \frac{200}{200+R} \times 24$ $R = 400 \Omega$	

25	D	$B = \mu_0 n I$ As the number of turns is halved, solenoid length is also halved, hence $n$ does not change. As $I = VR$ where $R = \rho L/A$ , since $L$ is halved, $R$ will be halved and $I$ will be twice as before. Hence $B_{\text{ext}}$ will be twice.
26	B	By Faraday's Law, the e.m.f. induced in the coil of wire rotating in a magnetic field is proportional to the rate of change of flux in the coil. $\mathcal{E} = - \frac{d\phi}{dt} = - \frac{d(MBA)}{dt}$ Hence e.m.f. does not depend on resistance of coil.
27	A	By Fleming's Right Hand Rule, the induced current will flow from Y to X inside the rod, which makes X the end with higher potential.
		Using $\mathcal{E} = Blv$ , we have $\mathcal{E} = 3.5 \times 0.80 \times 2.0 = 5.6 \text{ V}$ Thus, $P = \mathcal{E}^2 \div R = 5.6^2 / 6 = 5.23 \text{ W}$
28	C	Half-wave rectification is achieved with one diode: 
		For the above graph, $V_{\text{rms}} = \sqrt{\frac{V_0^2}{2}} = 0.71 V_0$
29	A	$(\Delta x)(\Delta my) \geq h$ $\Delta v \geq h / (0.25 \times 10^{-3} \times 5.30 \times 10^{-29}) = 5.0 \times 10^{-5} \text{ m s}^{-1}$
30	C	An alpha decay reduces nucleon number by 4 and proton number by 2. A beta decay maintains value of the nucleon number and increases proton by 1. Thus new nucleon number = $217 - 4 - 4 - 0 = 209$ And new proton = $85 - 2 - 2 + 1 = 82$ .



		(b)(iii)	Vertical component of $F$ $= 210 - 90 \sin(59^\circ)$ $= 133 \text{ N}$	C1
			Horizontal component of $F$ $= 90 \cos(59^\circ)$ $= 46 \text{ N}$	A1
			$F = (133^2 + 46^2)^{1/2} = 141$	C1 A1
2	(a)	Straight line passing through the origin which shows that $F$ and $x$ is proportional		B1
2	(b)(i)	Spring constant $= 5.6/0.04$ $= 140 \text{ N m}^{-1}$		B1
2	(b)(ii)	EPE $= \frac{1}{2}(5.6)(0.04)$ $= 0.11 \text{ J}$		B1
2	(c)(i)	Upthrust = Weight - Tension $= 6.2 - 5.6 = 0.60 \text{ N}$		A1
2	(c)(ii)	Pressure difference $= 0.60/(1.2 \times 10^{-3})$ $= 500 \text{ Pa}$		A1
2	(d)	If the liquid has a greater density, then the value of upthrust will increase. Since upthrust + spring force = weight, the value of spring force will decrease. Hence the extension will reduce.		M1
2	(e)	Percentage uncertainty of $h$ $= \left[ \frac{0.4}{6.2} + 2 \left( \frac{0.02}{1.95} + \frac{300}{7800} \right) \right] \times 100\%$ $= 13\%$		C1 A1

2022 Preliminary Examination H2Phy Paper 2 Suggested Solutions

1	(a)(i)	Using $v = u + at$ for vertical motion, $5.5 \sin(33^\circ) = -5.5 \sin(33^\circ) + (9.81)t$ $t = 0.61 \text{ s}$	C1 A1
	(a)(ii)	<b>Horizontal distance</b> $= 5.5 \cos(33^\circ) \times 0.61$ $= 2.8 \text{ m}$	C1 A1
	(a)(iii)	Ratio $= [5.5 \cos(33^\circ)]^2 / [5.5]^2$ $= 0.70$	C1 A1
		<b>Marker's comment:</b>	
	(b)(i)		
		Students must show that the lines of action of all 3 lines intersect at a common point.	B1
	(b)(ii)	Taking moment about B, $90 \times 6.0 = W \times 3.0 \cos(31^\circ)$ $W = 210 \text{ N}$	C1 A1

<b>3</b> <b>(a)</b>	<p>The gravitational potential at infinity is set at zero (as there is negligible g-force). Either of the following points,</p> <ul style="list-style-type: none"> <li>• The gravitational force is <b>attractive</b> and so the external force acting on the object is opposite in direction to the object's displacement as it moves from infinity to the point in question.</li> <li>• The celestial bodies are in a bound system. Work needs be given to separate them. Therefore, the system has negative potential.</li> <li>• At points that are less than infinity, the gravitational potential is negative as the test mass would lose gravitational potential energy when displaced from infinity (where GP is zero) to those points.</li> </ul> <p>Hence, the work done by the external force is negative which results in the gravitational potential having a negative value.</p> <p><b>Alternative</b></p> <p>The gravitational potential at infinity is set at zero. In bringing a point mass from infinity to a point in the gravitational field, the work done per unit mass by an external agent is <b>negative</b> as the force exerted on the point mass is opposite to its displacement from infinity. Hence, the gravitational potential has a negative value.</p>	<b>B1</b> <b>B1</b> <b>A0</b>
<b>4</b> <b>(a)</b>	<p>amplitude to amplitude = <math>2 x_0 = 9.8 \text{ cm}</math></p>	<b>A1</b>
<b>(a) (iii)</b>	$f = \frac{2700}{60} = 45 \text{ Hz}$	<b>A1</b>
<b>(a) (iii)</b>	$V = \omega \sqrt{x_0^2 - x^2}$ $= 2\pi \times 45 \times \sqrt{0.049^2 - (0.049 - 0.023)^2}$ $= 12 \text{ m s}^{-1}$	<b>C1</b> <b>A1</b>

<b>5</b> <b>(a)</b>	<p>First law of thermodynamics states that the increase in internal energy of a gas is the sum of the thermal energy supplied to the gas and the work done on the gas.</p>	<b>B1</b> <b>A1</b>
<b>(b) (i)</b>	<p>Using the ideal gas equation, <math>P = \frac{nRT}{V}</math></p> $P_i = \frac{nRT_i}{V_i} = \frac{nR(21.0 + 273.15)}{3.49 \times 10^{-6}} = nR(8.43 \times 10^4)$	<b>B1</b> <b>M1</b> <b>A0</b>
<b>(b) (ii)</b>	<p>The (net) gravitational field strength is equal to the negative gradient of the (net) gravitational potential – distance graph.</p> <p>Hence the direction of the net gravitational force is initially towards star A at <math>x = 0.1 \times 10^{12} \text{ m}</math>, zero at <math>0.52 \times 10^{12} \text{ m}</math> and finally towards star B thereafter.</p>	<b>B1</b> <b>B1</b>
<b>(b) (iii)</b>	<p>For the rock to reach the point where <math>x = 1.2 \times 10^{12} \text{ m}</math>, it must first be provided with a minimum amount of <b>energy</b> to reach the point of maximum gravitational potential (<math>-4.4 \times 10^8 \text{ J kg}^{-1}</math>). After that, the rock will be pulled towards star B.</p> <p><math>\text{GPE}_A + \text{KE}_A = \text{GPE}_{\text{max}}</math> (KE=0 at the peak of graph)</p> $m \phi_A + \min \text{KE} = m \phi_{\text{max}}$ $(180)(-10 \times 10^8) + (\frac{1}{2} \times 180 \times V^2) = (180)(-4.4 \times 10^8)$ $V = 3.3 \times 10^4 \text{ m s}^{-1}$	<b>M1</b> <b>A1</b>
<b>4</b> <b>(a)</b>	<p><math>x_0 = 4.9 \text{ cm}</math></p>	<b>A1</b>
<b>(a) (iii)</b>	$f = \frac{2700}{60} = 45 \text{ Hz}$	<b>A1</b>
<b>(a) (iii)</b>	$V = \omega \sqrt{x_0^2 - x^2}$ $= 2\pi \times 45 \times \sqrt{0.049^2 - (0.049 - 0.023)^2}$ $= 12 \text{ m s}^{-1}$	<b>C1</b> <b>A1</b>
<b>(b) (iii)</b>	$\Delta U = Q_{\text{in}} + W_{\text{on}}$ $= (+565) + (-160)$ $= 405 \text{ J}$	<b>C1</b> <b>A1</b>
<b>(b) (iv)</b>	<p>The internal energy of a real gas is defined as the sum of the microscopic kinetic energy and potential energy of the gas molecules. However, for an ideal gas, it is assumed that there are no intermolecular forces of attraction between the gas molecules. This means that the gas molecules do not possess microscopic potential energy.</p> <p>Hence, the change in its internal energy is totally due to the change in the total microscopic kinetic energies of the gas molecules.</p>	<b>B1</b> <b>B1</b> <b>B1</b> <b>A0</b>

6	(a)	Magnetic flux density is the force acting per unit current per unit length on a conductor placed at right angles to a magnetic field.	B1
	(b)(i)	The particle has a velocity component ( $v_y$ ) that is perpendicular to the $B$ -field and another component ( $v_x$ ) parallel to the $B$ -field. Due to $v_x$ always being perpendicular to the $B$ -field, there is magnetic force that is always perpendicular to $v_x$ , hence resulting in circular motion of the particle. Due to $v_x$ always being parallel to the $B$ -field, there is no magnetic force, hence resulting in linear motion of the particle. Combining the two motions, the resulting path is helical.	B1
	(ii)	The component of the velocity involves in the circular motion is $v_y = v \sin \theta$ . The magnetic force acting on the charge acts as its centripetal force.	B1

$$Bq v_y = \frac{mv_y^2}{r}$$

$$r = \frac{mv_y}{Bq} = \frac{mv \sin \theta}{Bq}$$

$$(iii) v \sin \theta = rw$$

Since  $r = \frac{mv \sin \theta}{Bq}$

$$v \sin \theta = \frac{mv \sin \theta}{Bq} \times \frac{2\pi}{T}$$

$$T = \frac{2\pi m}{Bq}$$

Since the expression for period  $T$  does not contain  $\theta$ ,  $T$  is independent of  $\theta$ .

7	(a)	The magnitude of the induced e.m.f. is directly proportional to the rate of change of magnetic flux linkage.	B1
	(b)(i)	Final flux linkage = $8.0 \times 10^{-3} \times 0.4 \times 10^{-4} \times 150$ = $4.8 \times 10^{-5} \text{ Wb}$ Initial flux linkage = $50 \times 10^{-3} \times 0.4 \times 10^{-4} \times 150$ = $3.0 \times 10^{-4} \text{ Wb}$ change = $  (4.8 \times 10^{-5}) - (3.0 \times 10^{-4})  $ = $2.52 \times 10^{-4} \text{ Wb}$	M1
	(ii)	Ave e.m.f. = $ \frac{\Delta \Phi}{\Delta t} $ = $\frac{2.52 \times 10^{-4}}{0.30}$ = $8.4 \times 10^{-4} \text{ V}$	M1
	(c)	The change in flux linkage over a given distance decreases when the coil is further from the magnet.	M1

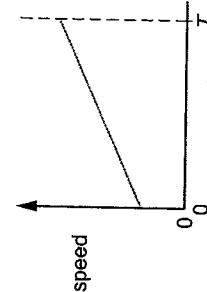
		For the induced emf to remain the same, the rate of change of flux linkage with respect to time must be constant. Thus, the speed of the coil should increase.	A1
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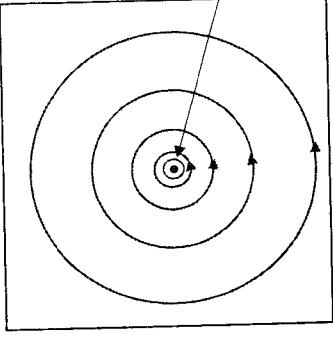
8	(a) (i)	In photoelectric effect, EM radiation releases electrons. In X-ray production, the reverse happens whereby electrons' acceleration or deceleration releases EM radiation.	B1
	(ii)	Maximum $I = P/V = 4 \times 10^3 / 40 \times 10^3 = 0.10 \text{ A} = 100 \text{ mA}$ Minimum $I = P/V = 4 \times 10^3 / 115 \times 10^3 = 0.0348 \text{ A} = 35 \text{ mA}$ Range of currents = $35 - 100 \text{ mA}$	M1
	(iii)	The rest of the kinetic energy of the electrons is transferred to the atoms (which causes the atoms to vibrate more vigorously). Or The rest of the kinetic energy is converted to heat.	A1
	(b)(i)	310	B1
	(ii)	3.6 3.2 2.8 2.4 2.0	B1

(iii)	$\text{Gradient} = (3.12 - 0.12) / (1640 - 40) = 1.875 \times 10^{-3} \text{ keV} \approx 1.9 \times 10^{-3} \text{ keV}$ Thus, $aE_1 = 1.9 \times 10^{-3} \text{ keV}$ $\Rightarrow E_1 = 1.9 \times 10^{-3} \text{ keV} / 0.139 = 13.7 \text{ eV}$ Or $E_1 = 1.875 \times 10^{-3} \text{ keV} / 0.139 = 13.5 \text{ eV}$	M1 A1
(iv)	Finding y-intercept: $3.12 = (1.9 \times 10^{-3})(1640) + c \Rightarrow c = 0.0040 \text{ keV}$ Or $3.12 = (1.875 \times 10^{-3})(1640) + c \Rightarrow c = 0.045 \text{ keV}$ Since $c \approx 0 \text{ keV}$ , this is consistent with the mathematical expression of Moseley's law which does not have a y-intercept. (Alternatively, students can read off the y-intercept and comment on the consistency.)	M1 A1
(v)	For the $K_{\alpha}$ line, $E = 0.75E_1(Z-1)^2 = 0.75(0.0137)(Z-1)^2$ Thus, $E = 0.75(0.0137)(74-1)^2 = 54.8 \text{ keV}$	M1 A1
(vi)	To show up on the X-ray spectrum of rhodium, the minimum energy of the incident electrons must be 2.70 keV. Thus, the minimum accelerating voltage must be 2.70 kV.	M1 A1
(c)(i)1	Intensity of X-ray beam emerging from model $= \frac{I_o e^{-(0.3)(10)}}{I_o}$ Intensity of X-ray beam incident on model $= I_o$ $= 0.0498$	A1
(i)2	Intensity of X-ray beam emerging from model $= \frac{I_o e^{-(0.3)(4)} e^{-(0.1)(6)}}{I_o}$ Intensity of X-ray beam incident on model $= I_o$ $= 2.64 \times 10^{-27}$	M1 A1
(ii)	The ratio of the ratios in (i) and (ii) is very large. Thus, the images will have good contrast	M1 A1

## 2022 YJC JC2 H2 Preliminary Examination Paper 3 Suggested Solutions

	(b)(i)	$v = \tau\omega$ $= (6.2)(2\pi/4.1)$ $= 9.5 \text{ m s}^{-1}$	C1 A1
	(b)(ii)	Acceleration $= \tau\omega^2$ $= (6.2)(2\pi/4.1)^2$ $= 14.6 \text{ m s}^{-2}$	C1 A1
	(b)(iii)	$R_B - \text{Weight} = \text{resultant force}$ $R_B - (75)(9.81) = (75)(14.6)$ $R_B = 1830 \text{ N}$	C1 A1
	(c)	$R_A = ma - mg$ , $R_A > 0$ is required to remain contact so $v^2/r > g$ , i.e. $v > \sqrt{rg}$ , the minimum speed for a contact force to be required	B1
	(d)	minimum speed is when $v^2/r = g$ $v^2/6.2 = 9.81$ $v = 7.8 \text{ m s}^{-1}$	B1
3	(a)	There is no lost volts or energy in the internal resistance of the battery OR With no internal resistance, the potential difference between A and C which is the terminal p.d. across the battery is equal to the e.m.f. of the battery.	B1
	(b)	As R is increased, the current I from the battery and hence flowing through Y decreases. With resistance of Y being constant, the p.d. across Y decreases	M1 A1
	(c)(i)	<b>Method 1</b> When $R = 6.0 \Omega$ , $I = 2.4 \text{ A}$ Hence $E = IR_{\text{total}}$ $24 = 2.4 \times R_{\text{total}}$ $R_{\text{total}} = 10 \Omega$ $R_{AB} + R_Y = R_{AB} + 6.0 = 10$ $R_{AB} = 4.0 \Omega$	A1
	(c)(ii)	<b>Method 2 (longer method)</b> When $R = 6.0 \Omega$ , $I = 2.4 \text{ A}$ Hence $E = IR_{\text{total}}$ $24 = 2.4 \times R_{\text{total}}$ $R_{\text{total}} = 10 \Omega$ $R_{AB} + R_Y = R_{AB} + 6.0 = 10$ $R_{AB} = 4.0 \Omega$	C1
2	(a)	Using potential divider rule, $V_{AB} = \frac{R_{AB}}{R_{\text{total}}} \times E = \frac{4.0}{10} \times 24$ $V_{AB} = 9.6 \text{ V}$	M1 A0
	(b)	For an object to move in circular motion at constant speed, it only changes direction hence, the change in velocity must be perpendicular to the direction of its velocity. Thus, the acceleration needs to be perpendicular to its velocity which leads to the resultant force being perpendicular to the velocity. Alternative: Since the object is moving at constant speed, its KE does not change. By Work-Energy Theorem, the work done by the resultant force must then be zero. Thus the resultant force must act perpendicular to its velocity.	B1 B1 B1

1	(a)	Using $v^2 = u^2 + 2as$ $8.7^2 = u^2 + 2(9.81)(1.5)$ $u = 6.8 \text{ m s}^{-1}$	C1 A1
	(b)	 speed t 0 Linear line and when $t = 0$ , speed is more than 0	B1
	(c)	When the ball hits the ground, it exerted a (normal) force on the ground. By Newton's third law, the ground exerts a (normal) force on the ball. The two forces are equal in magnitude but opposite in direction.	B1 B1
	(d)(i)	Change in momentum = final momentum – initial momentum $= (0.059)(5.4) - (0.059)(-8.7)$ $= 0.83 \text{ N s}$	C1 A1
	(d)(ii)	Resultant force on the ball $= 0.83/0.091$ Force by ground on ball $= 9.1 \text{ N}$ $= 9.1 + (0.059)(9.81)$ $= 9.7 \text{ N}$	C1 A1
	(e)	The resultant force will be equal to weight – air resistance. Air resistance increases with speed. Therefore, the resultant force and acceleration will decrease with time. Thus, the gradient of the graph will decrease with time.	B1 B1
2	(a)	For an object to move in circular motion at constant speed, it only changes direction hence, the change in velocity must be perpendicular to the direction of its velocity. Thus, the acceleration needs to be perpendicular to its velocity which leads to the resultant force being perpendicular to the velocity. Alternative: Since the object is moving at constant speed, its KE does not change. By Work-Energy Theorem, the work done by the resultant force must then be zero. Thus the resultant force must act perpendicular to its velocity.	B1 B1 B1

(c)(ii)	<p><b>Method 1</b></p> $V_{AB} = I_R \times R_{AB}$ $9.6 = 2.4 \times R_{AB}$ $R_{AB} = 4.0 \Omega$ $\frac{1}{R_x} + \frac{1}{R} = \frac{1}{R_{AB}}$ $\frac{1}{R_x} + \frac{1}{6.0} = \frac{1}{4.0}$ $R_x = 12 \Omega$	<p><b>Method 2</b></p> $V_R = I_R \times R$ $9.6 = I_R \times 6.0$ $I_R = 1.6 A$ $I = I_R + I_X$ $2.4 = 1.6 + I_X$ $I_X = 0.8 A$ $V_X = I_X \times R_X$ $9.6 = 0.8 \times R_X$ $R_X = 12 \Omega$
(c)(iii)	$P = IE$ $= 2.4 \times 24$ $= 57.6 W$	A1
(d)	With a constant e.m.f. and a decreasing current from battery OR With a constant e.m.f. and an increasing total resistance in the circuit the power provided by the battery decreases	A1 M0
4	<p>(a)(i)</p>  <p>Wire X with current flowing out of the plane.</p>	B1

(b)(i)	$B$ at wire Y due to wire X, $B = \frac{\mu_0 I_X}{2\pi X}$	C1
	$B = \frac{4\pi \times 10^{-7} \times 5.0}{2\pi \times 2.5 \times 10^{-2}}$ $= 4.0 \times 10^{-5} T$ $F = B I_Y L \sin \theta$ $F = 4.0 \times 10^{-5} \times 7.0 \times L \sin 90^\circ$ $\frac{F}{L} = 2.8 \times 10^{-4} N$	C1
(b)(ii)	The magnetic force acting on wire X due to wire Y and the magnetic force acting on wire Y due to wire X are a pair of action and reaction forces. According to Newton's 3 <sup>rd</sup> law, the forces on the two wires are equal in magnitude. <b>OR</b> The magnitude of the magnetic force depends on the product of the currents in the two wires. Hence the forces on the two wires are equal in magnitude.	M1 A1
(c)	$F_Y = B Y I_X L \sin \theta$ $F_Y = \frac{\mu_0 I_X \sin \omega t}{2\pi X} \times I_Y \sin \omega t \times L \sin \theta$ $F_Y = \frac{\mu_0 L I_X I_Y}{2\pi X} \times \sin^2 \omega t$ <p>Since <math>F_Y</math> is proportional to <math>\sin^2 \omega t</math>, the variation of the magnitude of the magnetic force is square of sinusoidal (or sinusoidal) OR</p> <p>the variation of the magnitude of the magnetic force is twice the frequency of the current.</p> <p>Since the currents are in phase, i.e. the currents in the two wires are always in the same direction, the magnetic forces acting on the wires are always attractive, (except when the currents in the wires are both zero).</p> <p>The direction of the magnetic force is always towards wire X (or leftwards or always in the same direction).</p> <p>(One mark to describe the magnitude and One mark to describe the direction)</p>	B1

5

5	(a)	The value of voltage that is equivalent to that of a steady d.c. voltage which will dissipate energy in a given resistor at the same rate.	B1 B1				
	(b)(i)	Squaring the graphs and arranging the curved portion to a rectangle.	M1				
		<p>Root-mean-square voltage = <math>10.39 \text{ V} = 10.4 \text{ V}</math></p>	A1				
	(b)(ii)	<table border="1"> <tr> <td>Diode 1</td> <td>Forward-biased</td> </tr> <tr> <td>Diode 2</td> <td>Reverse-biased</td> </tr> </table> <p>Both correct – [1] One or zero correct – [0]</p>	Diode 1	Forward-biased	Diode 2	Reverse-biased	B1 B1
Diode 1	Forward-biased						
Diode 2	Reverse-biased						
	(b)(iii)	<p>Effective resistance across resistors P and Q = <math>10/2 = 5 \Omega</math></p> <p>Using potential divider rule,</p> <p>Max p.d. across P = <math>\frac{5}{10+5}(12) = 4.0 \text{ V}</math></p>	B1 B1				
	(b)(iv)	<p>Correct waveform (shape) for two cycles <math>-12 \text{ V} &lt; V_p &lt; 12 \text{ V}</math> Numerical values of <math>V_p</math> not assessed</p>	B1 B1				

6

6	(a)(i)	either wavelength is longer than threshold wavelength or frequency is below the threshold frequency or photon energy is less than work function	B1
	(a)(ii)	$hc/\lambda = hf_0 + E_k$ $(6.63 \times 10^{-34} \times 3.00 \times 10^9) / (240 \times 10^{-9}) = 6.63 \times 10^{-34}f_0 + 4.44 \times 10^{-19}$ $f_0 = 5.8 \times 10^{14} \text{ Hz}$	C1
	(b)1.	photon energy larger so (maximum) kinetic energy is larger	A1
	(b)2.	fewer photons (per unit time) so (maximum) current is smaller	B1 B1 B1

## Section B

T	(a)	<ul style="list-style-type: none"> <li>The direction of the oscillations or vibrations is the key difference between longitudinal and transverse waves.</li> <li>For longitudinal waves, the vibrations are parallel to the direction of wave (or energy) travel.</li> <li>For transverse waves, the vibrations are perpendicular to the direction of wave (or energy) travel.</li> </ul> <p>(If student gave first point only one mark is awarded. If student gave second and third points, full marks are awarded)</p> <p>Transverse wave can be polarised but longitudinal wave cannot. [B1]</p>	B1
	(b)(i)	$I = \frac{P}{4\pi D^2}$ <p>Since intensity is proportional to the power of the sound source for fixed distance, the intensity is also halved when the power is halved</p> <p>Intensity is directly proportional to the square of the amplitude.</p> $\Rightarrow I = kA^2$ $\Rightarrow \frac{I_2}{I_1} = \left(\frac{A_2}{A_1}\right)^2$ $\Rightarrow \frac{1}{2} = \left(\frac{A_{\text{new}}}{A}\right)^2$ $\Rightarrow A_{\text{new}} = \frac{A}{\sqrt{2}} \quad \text{or} \quad 0.71A$	B1
	(b)(ii)	<p>Intensity from a point source follows the inverse square law.</p> <p>The sound intensity <math>I = \frac{P}{4\pi D^2}</math></p> <p>For the intensity to be the same,</p> $\frac{\frac{1}{2}P}{4\pi D'^2} = \frac{P}{4\pi D^2}$ $\Rightarrow D' = \frac{1}{\sqrt{2}}D = 0.71D$ <p>To make the perceived intensity return back to its original intensity, one must move closer to the sound source.</p>	C1 C1 A1

	(c)(i)	<p>The two waves are coherent because they have a constant phase difference (or constant phase relation) of <math>\pi</math> radian or <math>180^\circ</math>.</p> <p>From Fig. 7.2, the periods of both waves are same at ALL times.</p> <p>(Value of phase difference is not necessary)</p> <p>(Reject the following notions - having same frequency, period, speed etc. Two independent sources may have the same frequency but are not coherent because their phase relation may not be the same at all times.)</p>	B1
	(c)(ii)	<p>The two waves arrive at P in antiphase (<math>180^\circ</math>) to each other (crest of one meets the trough of the other wave) and so destructive interference takes place.</p> <p>However, it's only a partial cancellation as their amplitudes are not the same (they do not cancel completely). Hence, sound intensity at P is not zero but is a minimum.</p>	B1
	(c)(iii)	<p>The resultant intensity is <math>I</math>.</p> <p>No explanation is required here. After superposition, the resultant amplitude is still that of S alone. Thus, the intensity is the same as S alone.</p>	B1
	(c)(iv)	<p>From Fig. 8.2, period <math>T = 0.800</math> ms,</p> $c = f\lambda$ $330 = \left(\frac{1}{0.800 \times 10^{-3}}\right)\lambda$ $\lambda = 0.264 \text{ m}$	M1 A1
	(d)(i)	<p>P and O are successive minima and so the path difference must be one wavelength, <math>\lambda = 0.264 \text{ m}</math></p>	B1
	(d)(ii)	<p>Since P is the first minimum after O, the path difference (TP-SP) = <math>\lambda</math></p> <p>Thus, <math>\sin\theta = \frac{\lambda}{a} = \frac{0.264}{0.50} = 0.528</math></p> $\Rightarrow \theta = 31.9^\circ$	C1 A1
	(d)(iii)	<p>Looking at triangle TPR, we have</p> $PR = PO + OR = (2.40 + 0.25) \text{ m} = 2.65$	C1

<p><b>8</b></p> <p>(a)(i) To remove air from the chamber, so that alpha particles can successfully travel from the source to the foil and to the screen.</p> <p>(a)(ii) To detect the alpha particles, via scintillations / flashes of light, there must not be other significant sources of light in the room.</p> <p>(a)(iii)</p> <p>Either</p> <p>Observation: A very small fraction of the <math>\alpha</math>-particles was deflected through very large angles</p> <p>Implication: The nucleus has <u>large mass and (positive) charge</u></p> <p>Or</p> <p>Observation: Most of the <math>\alpha</math>-particles were hardly deflected</p> <p>Implication: The nucleus is <u>very small in size</u> / Most of the atom is empty space</p>	<p>B1 B1</p> <p>B1 B1</p> <p>B1</p>
<p>(a)(iv)</p>	
	<p>Deflection is away from nucleus and the upper alpha particle has <u>greater</u> deflection angle</p> <p>Change in direction occurs <u>before</u> the point directly below nucleus</p> <p>Sharp deflection – max of [1]</p>
<p>(b)(i)</p>	$E = m c^2$ $= (1.0 \times 1.66 \times 10^{-27}) (3.0 \times 10^8)^2$ $= 1.494 \times 10^{-10} \text{ J}$ $= 1.494 \times 10^{-10} / 1.6 \times 10^{-19} \text{ eV}$ $= 934 \text{ MeV}$

	$\tan \theta = \frac{x}{d} \Rightarrow \tan 31.9 = \frac{2.40 + 0.25}{d} = \frac{2.65}{d}$ $d = 4.3 \text{ m}$ <ul style="list-style-type: none"> <li>Note that <math>\sin 31.9^\circ</math> is not the same as <math>\tan 31.9^\circ</math></li> <li>Reject solving using <math>\lambda = \frac{ax}{D}</math> (which yields <math>d = 4.5 \text{ m}</math>).</li> <li>The <math>\lambda = \frac{ax}{D}</math> is valid only if <math>a &lt; D</math>.</li> </ul>	C1 A1
(d)(iii)	<p>The Young's double slit interference equation was derived based on the approximation that the wavelength <math>\lambda</math> is very small compared to the slit separation <math>a</math>, or that the slit separation <math>a</math> is much smaller than <math>d</math>. In part (d)(ii)1, the angle <math>\theta (31.9^\circ)</math> is large. Here, we see that <math>\sin \theta = \frac{\lambda}{a} = \frac{0.264}{0.50} = 0.53</math>, and so the wavelength is not very small, compared to the source separation.</p> <p>In part (d)(ii)2,</p> $\frac{a}{d} = \frac{0.50}{4.3} = 0.11$ <p>Thus, the assumption does not satisfy the approximation condition where <math>\theta \approx \sin \theta</math> and so we cannot use the equation <math>\lambda = \frac{ax}{D}</math>.</p>	M1 A1
(e)	<p>Polarisation is a phenomenon associated with transverse waves only. Sound is a longitudinal wave and as such is not affected by polarisation.</p>	B1

(b)(ii)	Energy absorbed to separate a nucleus into its constituent free/unbound protons and neutrons Or Energy released to form a nucleus from its constituent free/unbound protons and neutrons	B1 B1
(b)(iii)	Mass defect of $Zr = (40 \times 1.0073) + (57 \times 1.0087) - (97.0980)$ $= 97.7879 - 97.0980$ $= 0.6899 \text{ u}$	C1
	B.E. per nucleon = $644.37 / 97 = 6.64 \text{ MeV/nucleon}$	C1 A1
(c)(i)	Spontaneous decay means that the rate of decay is not affected by external factors such as pressure, temperature, etc. Or Decay occurs on its own, without external stimuli	B1
(c)(ii)	The curve has local fluctuations / jagged edges	B1
(c)(iii)	1. Gamma rays/photons 2. Alpha-particles 3. Gamma 4. Beta-particles All four correct – [2]	
	Subtract [1] for any wrong answer. Minimum is [0]	
(c)(iv)	The energy released is shared by the daughter nucleus, beta particle and a neutrino / anti-neutrino.	B1



CANDIDATE  
NAME

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CG

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INDEX NO

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**PHYSICS**

**Marking Scheme**

**9749/04**

Paper 4 Practical

25 Aug 2022

2 hours 30 minutes

Candidates answer on the Question Paper.  
No Additional Materials are required.

**READ THESE INSTRUCTIONS FIRST**

Write your name and class in the spaces at the top of this page.

Write in dark blue or black pen on both sides of the paper.

You may use an HB pencil for any diagrams, graphs or rough working.

Do not use staples, paper clips, highlighters, glue or correction fluid/tape.

Answer all questions.

Write your answers in the spaces provided on the question paper.  
The use of an approved scientific calculator is expected, where appropriate.

You may lose marks if you do not show your working, where appropriate, in the boxes provided.

Give details of the practical shift and laboratory, where appropriate, in the boxes provided.

At the end of the examination, fasten all your work securely together. The number of marks is given in brackets [ ] at the end of each question or part question.

Shift
Laboratory

For Examiner's Use
1 / 14
2 / 6
3 / 23
4 / 12
Total / 55

**1** In this experiment you will investigate an electrical circuit.

**3**

<p><b>(b)</b> Change the labelled resistor R and repeat (a). Present your results clearly.</p>	<table border="1" data-bbox="1002 1376 1349 2004"> <thead> <tr> <th data-bbox="1009 1380 1067 1423">R/<math>\Omega</math></th><th data-bbox="1009 1380 1067 1423"><math>y/\text{cm}</math></th><th data-bbox="1009 1380 1067 1423"><math>y_2/\text{cm}</math></th><th data-bbox="1009 1380 1067 1423"><math>y/\text{cm}</math></th><th data-bbox="1009 1380 1067 1423"><math>\frac{1}{y} / \text{cm}^{-1}</math></th></tr> </thead> <tbody> <tr> <td data-bbox="1009 1423 1067 1457">150</td><td data-bbox="1009 1423 1067 1457">34.1</td><td data-bbox="1009 1423 1067 1457">33.9</td><td data-bbox="1009 1423 1067 1457">34.0</td><td data-bbox="1009 1423 1067 1457">0.0294</td></tr> <tr> <td data-bbox="1009 1457 1067 1490">220</td><td data-bbox="1009 1457 1067 1490">26.3</td><td data-bbox="1009 1457 1067 1490">26.8</td><td data-bbox="1009 1457 1067 1490">26.6</td><td data-bbox="1009 1457 1067 1490">0.0376</td></tr> <tr> <td data-bbox="1009 1490 1067 1524">330</td><td data-bbox="1009 1490 1067 1524">19.6</td><td data-bbox="1009 1490 1067 1524">20.2</td><td data-bbox="1009 1490 1067 1524">19.9</td><td data-bbox="1009 1490 1067 1524">0.0503</td></tr> <tr> <td data-bbox="1009 1524 1067 1564">470</td><td data-bbox="1009 1524 1067 1564">15.3</td><td data-bbox="1009 1524 1067 1564">15.5</td><td data-bbox="1009 1524 1067 1564">15.4</td><td data-bbox="1009 1524 1067 1564">0.0649</td></tr> <tr> <td data-bbox="1009 1564 1067 1598">680</td><td data-bbox="1009 1564 1067 1598">10.7</td><td data-bbox="1009 1564 1067 1598">11.1</td><td data-bbox="1009 1564 1067 1598">10.9</td><td data-bbox="1009 1564 1067 1598">0.0917</td></tr> <tr> <td data-bbox="1009 1598 1067 1632">820</td><td data-bbox="1009 1598 1067 1632">8.5</td><td data-bbox="1009 1598 1067 1632">9.0</td><td data-bbox="1009 1598 1067 1632">8.8</td><td data-bbox="1009 1598 1067 1632">0.11</td></tr> </tbody> </table>	R/ $\Omega$	$y/\text{cm}$	$y_2/\text{cm}$	$y/\text{cm}$	$\frac{1}{y} / \text{cm}^{-1}$	150	34.1	33.9	34.0	0.0294	220	26.3	26.8	26.6	0.0376	330	19.6	20.2	19.9	0.0503	470	15.3	15.5	15.4	0.0649	680	10.7	11.1	10.9	0.0917	820	8.5	9.0	8.8	0.11
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<p>Plot <math>\frac{1}{y}</math> against R with expected gradient a and vertical intercept ab</p> <p>Gradient, <math>a = \frac{0.110 - 0.030}{840 - 160} = 1.18 \times 10^{-4} \text{cm}^{-1}\Omega^{-1}</math></p> <p>Vertical intercept = <math>0.110 - (1.18 \times 10^{-4})(840) = 1.09 \times 10^{-2}</math></p> <p><math>b = (1.09 \times 10^{-2})/(1.18 \times 10^{-4}) = 92.4 \Omega</math></p>	<p>- Correct header with unit [1]</p> <p>- 6 sets of data [1]</p> <p>- Reading recorded with correct precision and values calculated to correct s.f [3]</p> <p>It is suggested that the quantities y and R are related by the equation</p> $\frac{1}{y} = a(R + b)$ <p>where a and b are constants.</p> <p>Plot a suitable graph to determine a and b.</p> <p>- Correct linearisation (look out for the linearisation statement) [1]</p> <p>- Correct calculation of a with units and s.f [1]</p> <p>- Correct calculation of b with units and s.f [1]</p> <p>- Graph with appropriate scale [1]</p> <p>- All data points correctly plotted [1]</p> <p>- Appropriate best fit line drawn [1]</p>																																			

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- 2 In this experiment, you will investigate the result of a collision between two cylinders.

(a) The thicker wooden cylinder has diameter  $D$ .

Measure and record  $D$ .

- $D$  measured to the correct precision (1 d.p in mm, 2 d.p in cm)
- Check accuracy of  $D$
- Repeated reading for both  $D$  and  $d$

$$\frac{1}{2}(1.59 + 1.59) = 1.59 \text{ cm}$$

$$D = \dots\dots\dots\dots\dots\dots\dots [1]$$

(b) The thinner wooden cylinder has diameter  $d$ .

Measure and record  $d$ .

- $d$  measured to the correct precision (1 d.p in mm, 2 d.p in cm)
- Check accuracy of  $d$
- Repeated reading for  $d$

$$\frac{1}{2}(0.63 + 0.63) = 0.63 \text{ cm}$$

$$d = \dots\dots\dots\dots\dots\dots\dots [1]$$

(c) (i) You have been provided with a wooden ruler with a line drawn on the face without the scale.

Use the stand, boss and clamp to set up the ruler in the position shown in Fig. 2.1. The end near the line should touch the cork board and the other end should be approximately 7 cm above the bench.

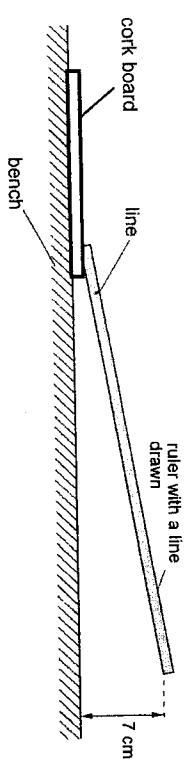


Fig 2.1

Place the cylinder with smaller diameter approximately 8 cm from the end of the wooden ruler.

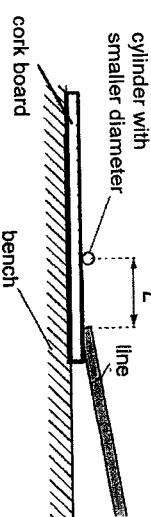


Fig 2.2

The distance between the end of the ruler and the cylinder is  $L$ , as shown in Fig. 2.2.

Measure and record  $L$ .

$$L = \dots\dots\dots\dots\dots\dots\dots [1]$$

(ii)

Place cylinder with smaller diameter on the line on the ruler is shown in Fig 2.2.

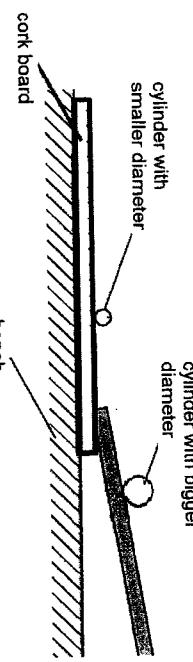


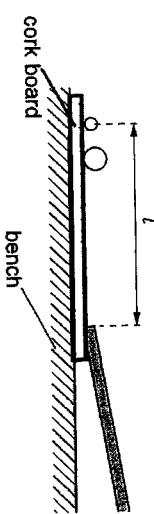
Fig 2.3

Release the cylinder of the bigger diameter.

It will roll down the ruler and on the cork board until it collides with the cylinder of the smaller diameter.

The cylinder of the smaller diameter will roll and then come to rest as shown in Fig. 2.4.

The distance between the cylinder of smaller diameter and the end of the ruler is  $l$ , as shown in Fig. 2.4.



Measure and record  $l$ .

- $l$  is measured to the correct precision (1 d.p in cm)
- repeated reading
- $l$  is more than  $L$

$$l = \dots\dots\dots\dots\dots\dots\dots [1]$$

$$16.9 \text{ cm}$$

$$\frac{1}{2}(17.2 + 16.6) = 16.9 \text{ cm}$$

- (d) It is suggested that the relationship between  $l$ ,  $L$ ,  $D$  and  $d$  is  

$$(l-L)^2 = z(D-d)^3$$

where  $z$  is a constant.

- (i) Using your data, calculate  $z$ .

- $z$  is calculated correctly and with the appropriate s.f
- $z$  is reported with appropriate units [cm<sup>-1</sup>]

$$z = \frac{(1.59-0.63)^3}{(16.9-8.0)} = 0.11 \text{ cm}^{-1}$$

$$z = ..... \text{cm}^{-1} \quad [1]$$

- (ii) If you were to repeat this experiment using a similar wooden ruler and cylinders but with different starting position of the cylinder with smaller diameter, describe the graph that you would plot and how can  $z$  be determined from the graph.

- Plot  $l$  against  $L$  [1]
- $z$  can then be determined from the vertical intercept as the vertical intercept will be  $z^{1/2}(D-d)^{3/2}$  [1]

Any other logical linearisation can be accepted

[Total: 6]

- 3 In this experiment, you will investigate the motion of a loaded plastic ruler.

- (a) Assemble the apparatus as shown in Fig. 3.1.

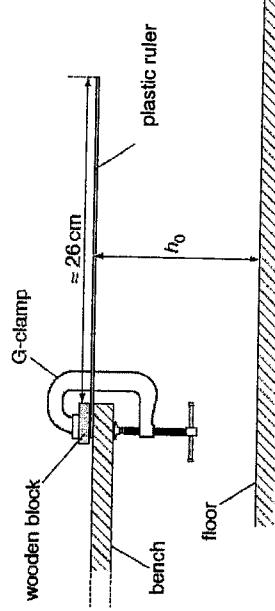


Fig. 3.1 (not to scale)

The vertical distance from the floor to the top surface of the plastic ruler is  $h_0$ , as shown in Fig. 3.1.

Measure and record  $h_0$ .

Value of  $h_0$  with unit and to the nearest mm [1]

$h_0 = ..... \text{cm or } 0.895 \text{ m} \quad [1]$

- (b) (i) Place the 50 g slotted mass on the plastic ruler with its centre approximately 19 cm from the bench and tape it in position.

When released, the plastic ruler will bend down, as shown in Fig. 3.2.

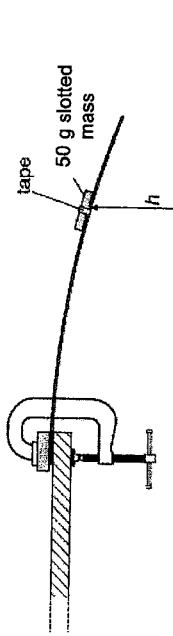


Fig. 3.2 (not to scale)

The vertical distance from the floor to the top surface of the plastic ruler at the centre of the mass is  $h$ .

Value of  $h$  with unit and value of  $h$  less than  $h_0$  [1]

(ii) Calculate  $y$ , where  $y = h_0 - h$ .

$$y = 0.895 - 0.808 = 0.087 \text{ m}$$

Correct calculation of  $y$  with unit following the d.p. of  $h_0$  and  $h$

$$y = ..... \text{cm or } 0.087 \text{ m} \quad [1]$$

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- (c) (i) Estimate the percentage uncertainty in your value of  $y$ .

$$\text{Percentage Uncertainty} = \frac{\Delta y}{y} \times 100\% = \frac{0.003}{0.087} \times 100\%$$

Absolute uncertainty in  $y$  of 3 to 6 mm  
Correct calculation and to 2.s.f.

$$= 3.4\% \quad \text{percentage uncertainty} = 3.4\% \quad [1]$$

- (ii) Suggest one significant source of uncertainty in this experiment.  
The metre rule may not be vertical (hence it is difficult to measure  $h_0$  or  $h$ ).....

It is difficult to judge the position of the centre of mass (hence it is difficult to measure  $h$ ).  
The plastic rule is bent or is not horizontal (hence it is difficult to measure  $h$ ). [1]

- (iii) Suggest an improvement that could be made to the experiment to reduce the uncertainty identified in (ii).

You may suggest the use of other apparatus or a different procedure.  
Use a set square on floor or plumb line or spirit level to check that metre rule is vertical.

Mark and measure  $h$  at the position for the centre of mass on the plastic ruler.....

Clamp the rule and use a set square as a pointer ..... [1]

- (d) Push the end of the plastic ruler down a small distance and then release it. The plastic ruler will oscillate.

Determine the period of  $T$  of the oscillations.

$$T = \frac{22.36 + 22.27}{2(40)} = 0.5579 \text{ s}$$

Evidence of repeat readings of time where  $nT \geq 20$  s  
Value of  $T$  in range 0.5 s to 0.6 s  
 $T$  expressed in 4.s.f. based on raw data

$$T = \dots \quad 0.5579 \text{ s} \quad [2]$$

- (e) Move the slotted mass approximately 3 cm further from the bench and fix it with tape.

Measure and record  $h$ .

Second value of  $h$  which is smaller than the first value

$$h = \dots \quad 78.0 \text{ cm or } 0.780 \text{ m} \dots$$

- Repeat (b)(ii) and (d).

$$y = 0.895 - 0.780 = 0.115 \text{ m}$$

$$y = \dots \quad 11.5 \text{ cm or } 0.115 \text{ m} \dots$$

$$T = \frac{25.16 + 25.01}{2(40)} = 0.6271 \text{ s}$$

Second value of  $T$  with unit  
Second value of  $T$  is greater than the first value

$$0.6271 \text{ s} \quad [3]$$

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- (f) It is suggested that the relationship between  $T$  and  $y$  is

$$T = c\sqrt{y}$$

where  $c$  is a constant.

- (i) Using your data, calculate two values of  $c$ .

$$1^{\text{st}} \text{ value: } T = c\sqrt{y}$$

$$0.5579 = c\sqrt{0.087}$$

$$c = 1.891$$

$$2^{\text{nd}} \text{ value: } T = c\sqrt{y}$$

$$0.6271 = c\sqrt{0.115}$$

$$c = 1.894$$

first value of  $c = \dots \quad 1.9 \dots$   
second value of  $c = \dots \quad 1.89 \dots$

[1] Correct calculation of two values of  $c$

- (ii) Justify the number of significant figures given for your values of  $c$ .  
The number of significant figures for  $c$  follows the lowest significant figures for  $y$  and  $T$ .

Since  $y$  has the lowest s.f. of 2 or 3 s.f.,  $c$  also has 2 or 3 s.f. respectively. [1]

- (iii) State whether the results of your experiment support the suggested relationship.

Justify your conclusion by referring to your answers in c(ii).

Percentage difference =  $\frac{c_{\text{bigger}} - c_{\text{smaller}}}{c_{\text{smaller}}} \times 100\% = \frac{1.9 - 1.89}{1.89} \times 100\% = 0.53\%$

Percentage uncertainty =  $\frac{1}{2} \frac{\Delta y}{y} \times 100\% = \frac{1}{2} \times 3.4\% = 1.7\%$

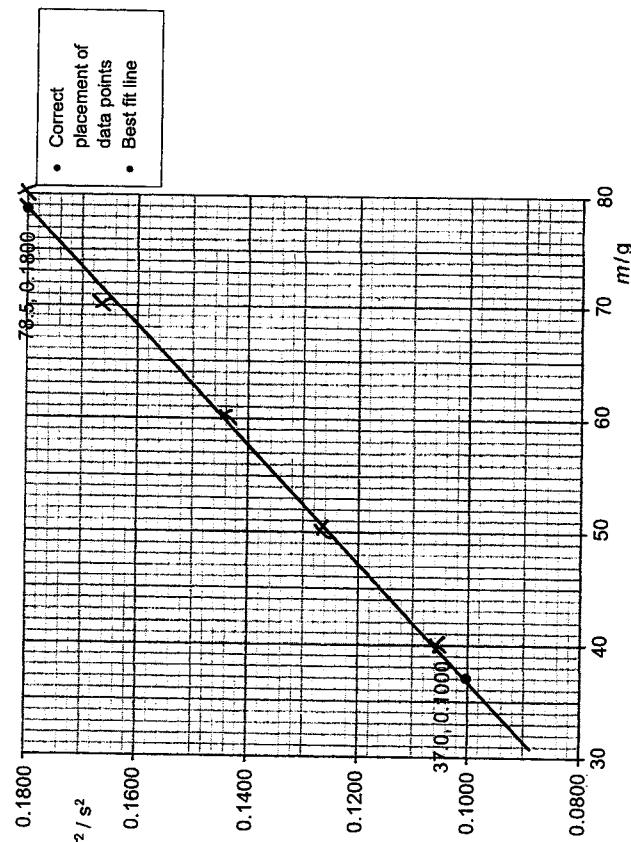
Since the percentage difference is smaller than the calculated percentage uncertainty of  $c$ , the results support the suggested relationship. [1]

- (g) In an investigation, the mass  $m$  of the slotted mass attached to the centre of the plastic rule was varied.

The following results for  $m$  and  $T$  were recorded. The value of  $T^2$  is then calculated.

$m / g$	40	50	60	70	80
$T / s$	0.3250	0.3555	0.3794	0.4074	0.4243
$T^2 / s^2$	0.1056	0.1264	0.1439	0.1660	0.1800

- (i) Plot  $T^2$  against  $m$  on the grid and draw the straight line of best fit. [2]



- (ii) Use your graph to determine the value of  $T$  when no mass is attached to the plastic rule.

$$\text{Gradient} = \frac{y_2 - y_1}{x_2 - x_1} = \frac{0.1800 - 0.1000}{78.5 - 37.0}$$

$$\text{Gradient} = 0.001928$$

$$y = mx + c \quad \text{where } c = T^2 \\ 0.1800 = 0.001928 \times 78.5 + T^2 \\ T^2 = 0.02865 \text{ (y-intercept)}$$

$$T = 0.169 \text{ s} \\ T = \dots \dots \dots \text{ s} [3]$$

- (h) The behaviour of the loaded plastic ruler depends on the thickness of the plastic ruler. It is suggested that the square of the period  $T$  is inversely proportional to the cube of the thickness  $b$  of the plastic ruler.

Explain how you would investigate this relationship.

Your account should include:

- your experimental procedure
- control of variables
- how you would use your results to show inverse proportionality
- why you might have difficulties using very thin plastic rulers

1. The independent variable is the thickness  $b$  of the plastic ruler.
2. The dependent variable is the period  $T$  of the oscillating loaded plastic ruler.
3. The control variables are the mass of the slotted load attached, the breadth of the plastic ruler, the position at which the mass is attached to the plastic ruler. [C1]
4. Set up the apparatus as shown in Fig. 3.1.
5. Measure the thickness  $b$  of the plastic ruler using a vernier callipers. [M]
6. Push the end of the ruler downwards and let it oscillate.
7. Measure the time taken  $t$  to complete  $n$  oscillations (such that  $t$  is greater than 20 s) using a stopwatch. [M]
8. Repeat step 6 and 7 and take the average of the two timings.
9. Calculate the period of the oscillating loaded plastic ruler using  $T = (t_1 + t_2) / 2n$ . [M]
10. Repeat steps 5 to 9 for another seven times with different thickness of the plastic ruler.
11. Plot a graph of  $T^2$  against  $1/b^3$ . If the best fit line is a straight line passing through origin,  $T^2$  is inversely proportional to  $b^3$ .
12. When the plastic ruler is too thin, the loaded plastic ruler may break easily.

- [C1] Stating the two control variables.  
 [M1] Measurement of  $L$  and  $t$  and the calculation of  $T$   
 [A1] Analysis of the results to prove the inverse proportional relationship of  $T^2$  and  $b^3$ .  
 [D1] State any appropriate difficulty faced when using a thin plastic ruler.

[Total: 23]

- 4 An aluminium ring is placed on a coil with the rod of a metal retort stand passing through their centres, as shown in Fig. 4.1.

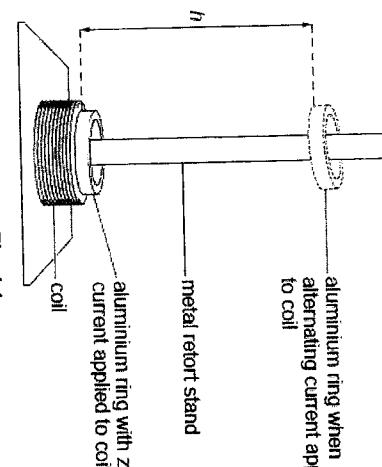


Fig. 4.1

The aluminium ring has a thickness  $b$ .

When an alternating current of frequency  $f$  is applied to the coil, the ring rises until it is in equilibrium at a height  $h$  above the coil.

The height  $h$  that the aluminium ring rises until it is in equilibrium is given by

$$h = k f^p b^q$$

where  $k$ ,  $p$  and  $q$  are constants.

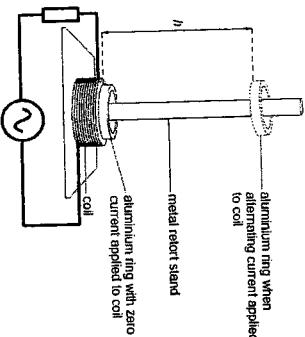
Design an experiment to determine the values of  $p$  and  $q$ .

You would be provided with several aluminium rings with different thicknesses.

Draw a diagram to show the arrangement of your apparatus. Pay particular attention to:

- (a) the equipment you would use
- (b) the procedure to be followed
- (c) how the frequency of the alternating current, thickness of ring and height risen are measured
- (d) the control of variables
- (e) any precautions that should be taken to improve the accuracy and safety of the experiment.

**Diagram**



Exp 1

- 7 Close the switch.

- 8 Read off the frequency  $f$  of the alternating current stated in the signal generator or variable frequency power generator. Or The frequency  $f$  of the alternating current measured determined by the period  $T$  of the alternating current measured by an oscilloscope. Using the formula  $f = 1/T$ . [M2]

- 9 Measure the height  $h$  that the aluminium ring has risen using a rule. [M3]

- 10 Repeat the experiment with another 7 sets of frequency  $f$  by adjusting the frequency knob of the signal generator while keeping the thickness of the ring constant. [M4]

Exp 2

- 11 Measure the thickness of the aluminium ring using a vernier calliper. [M3]

- 12 Close the switch.

- 13 Measure the height  $h$  that the aluminium ring has risen using a rule.

- 14 Repeat the experiment with another 7 sets of thickness  $b$  by using aluminium ring of different thickness while keeping the frequency of alternating current constant. [M5]

**Analysis (2 marks)**

- 15..Plot a graph of  $\lg h$  against  $\lg f$ : if the best fit line is a best-fitted straight line; the gradient of best fit line is the value of  $p$ . [A1]

- 16..Plot a graph of  $\lg h$  against  $\lg b$ : if the best fit line is a best-fitted straight line; the gradient of best fit line is the value of  $q$ . [A2]

**Safety consideration (1 Mark)**

17. Switch off when not in use to prevent the coil from overheating. (Do not allow small current as the current needs to be large enough for the height to be measurable). [S1]

18. Do not touch the hot coil or Use gloves to prevent any injury from the hot coil. [S1]

**Defining the problem (2 marks)**

1. The aim of the experiment is to find the unknown  $p$  and  $q$  in the relation  $h = K f^p b^q$

2. The two independent variables are the frequency  $f$  of the alternating current and the thickness  $b$  of the aluminium ring.

3. The dependent variable is the height  $h$  that the aluminium ring rises. [D1]

4. The two sets of experiment are to be carried out

- (1)  $h$  and  $f$  kept constant  
(2)  $h$  and  $b$  with  $f$  kept constant

5. The control variables are the (rms) current in the coil, diameter of the aluminium ring, number of turns of the coil. (State at least 2 control variables) [CT]

**Data Collection (X marks)**

6. Set up the apparatus as shown earlier.

**Exp 1**

- 7 Close the switch.

- 8 Read off the frequency  $f$  of the alternating current stated in the signal generator or variable frequency power generator. Or The frequency  $f$  of the alternating current measured determined by the period  $T$  of the alternating current measured by an oscilloscope. Using the formula  $f = 1/T$ . [M2]

- 9 Measure the height  $h$  that the aluminium ring has risen using a rule. [M3]

- 10 Repeat the experiment with another 7 sets of frequency  $f$  by adjusting the frequency knob of the signal generator while keeping the thickness of the ring constant. [M4]

Exp 2

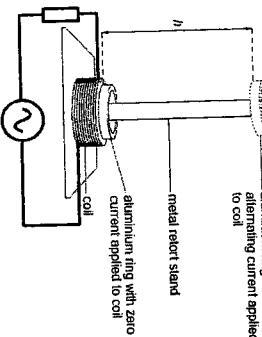
- 11 Measure the thickness of the aluminium ring using a vernier calliper. [M3]

- 12 Close the switch.

- 13 Measure the height  $h$  that the aluminium ring has risen using a rule.

- 14 Repeat the experiment with another 7 sets of thickness  $b$  by using aluminium ring of different thickness while keeping the frequency of alternating current constant. [M5]

**Diagram**



**Additional details (2 marks)**

19. Connect a variable resistor to the circuit so that the current flowing through the coil can be monitored to be constant (using an ammeter).
20. Use iron (or steel) rod to increase the change in magnetic field that the ring experiences to have measurable height.
21. Use coil of many turns or large current to have measurable height.
22. A set square is used to ensure metre rule is vertical when measuring  $h$ .
- Any two of the additional details.

[Total: 12]

